

Basic Non Fail-Safe modulating actuator for controlling dampers in typical commercial HVAC applications.

- Torque motor 45 in-lb [5 Nm]
- Nominal voltage AC/DC 24 V
- Control modulating
- Position feedback 2...10 V



Technical data sheet



LMCB24-SR-T



Technical data

Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	1.5 W
	Power consumption in rest position	0.4 W
	Transformer sizing	3 VA
	Electrical Connection	Screw terminal (for 26 to 14 GA wire)
	Overload Protection	electronic throughout 095° rotation
Functional data	Torque motor	45 in-lb [5 Nm]
	Operating range Y	210 V
	Operating range Y note	420 mA w/ ZG-R01 (500 Ω, 1/4 W resistor)
	Input impedance	100 kΩ for 210 V (0.1 mA), 500 Ω for 420 mA
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Direction of motion motor	selectable with switch 0/1
	Manual override	external push button
	Angle of rotation	Max. 95°
	Angle of rotation note	adjustable with mechanical stop
	Running Time (Motor)	35 s / 90°
	Running time motor note	constant, independent of load
	Noise level, motor	45 dB(A)
	Position indication	Mechanical, 3065 mm stroke
Safety data	Power source UL	Class 2 Supply
	Degree of protection IEC/EN	IP20
	Degree of protection NEMA/UL	NEMA 1
	Enclosure	UL Enclosure Type 1
	Agency Listing	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02
		CE acc. to 2014/30/EU and 2014/35/EU
	Quality Standard	ISO 9001
	UL 2043 Compliant	Suitable for use in air plenums per Section 300.22(C) of the NEC and Section 602 of the IMC
	Ambient humidity	Max. 95% RH, non-condensing
	Ambient temperature	-22122°F [-3050°C]
	Storage temperature	-40176°F [-4080°C]
	Servicing	maintenance-free
Weight	Weight	100 lb [0.45 kg]
Materials	Housing material	UL94-5VA



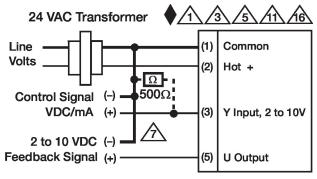
Technical data sheet

Footnotes	†Rated Impulse Voltage 800V, Type action 1, Control Pollution Degree 3.	
Product features		
Application	For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft from 1/4" up to 5/8" in diameter by means of its universal clamp. Shafts up to 3/4" diameter can be accommodated by an accessory clamp. The actuator operates in response to a 210 V, or with the addition of a 500 Ω resistor, a 420 mA control input from an electronic controller or positioner. A 210 V feedback signal is provided for position indication or primary/ secondary operation.	
Operation	The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.	
	The LMB series provides 95° of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.	
	The LMCB24-SR actuators use a sensorless brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.	
	Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.	
Typical specification	Proportional control damper actuators shall be electronic direct-coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft from 1/4" to 5/8". Shafts up to 3/4" diameter can be accommodate with an accessory clamp. Actuators must provide proportional damper control in response to a 2 to 10 VDC or, with the addition of a 500 Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. If required, actuator will be provided with screw terminal strip for electrical connections (LMCB24-SR-T). Run time shall be constant and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position indication. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.	
Accessories		

Accessories

Electrical accessories	Description	Туре	
	Battery backup system, for non-spring return models	NSV24 US	
	Battery, 12 V, 1.2 Ah (two required)	NSV-BAT	
	Feedback potentiometer 140 Ω add-on, grey	P140A GR	
	Feedback potentiometer 500 Ω add-on, grey	P500A GR	
	Feedback potentiometer 1 k Ω add-on, grey	P1000A GR	
	Feedback potentiometer 2.8 kΩ add-on, grey	P2800A GR	
	Feedback potentiometer 5 k Ω add-on, grey	P5000A GR	
	Feedback potentiometer 10 k Ω add-on, grey	P10000A GR	
	Auxiliary switch 1 x SPDT add-on	S1A	
	Auxiliary switch 2 x SPDT add-on	S2A	
Electrical installation			
	 Provide overload protection and disconnect as required. Actuators may also be powered by DC 24 V. Only connect common to negative (-) leg of control circuits. A 500 Ω resistor (ZG-R01) converts the 420 mA control signal to 210 V. Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed. Actuators are provided with a numbered screw terminal strip instead of a cable. 		





2...10 V / 4...20 mA Control

Dimensions

